

COPY

ATTACHMENT 1(g)

	ALTORNET DOCKET NO.	APPLICATION NO.		
	392.1682	09/546,213		
LIST OF ADDITIONAL SUBMITTED	FIRST NAMED INVENTOR			
DOCUMENTS	Atsushi WATANABE			
boodine!!!O	FILING DATE	GROUP ART UNIT		
	April 10, 2000	2625		

The following document(s) is/are listed in accordance with the duty of disclosure provisions of 37 CFR § 1.56, so that the Examiner may consider same should he deem any thereof to be material to examination of the subject application.

It is requested that the Examiner acknowledge his consideration of document(s) below-listed by initialling same in the space provided adjacent each such application and that the Examiner sign and date this form at the bottom thereof to confirm such consideration having been given.

This submission in no way represents an admission that any of the information listed herein constitutes prior art with respect to the subject application; and unless and until such prior art status is established, this submission is not a request that the information presented herein be printed on the face of any patent issuing from the subject application in which this information is being filed.

U.S. PATENT DOCUMENTS

*EXAMINER INITIAL		DOCUMENT NO.	DATE	NAME	CLASS	SUB- CLASS	FILING DATE
	AA						
	AB						
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FOREIGN PATENT DOCUMENTS

		DOCUMENT NO.	DATE	COUNTRY	CLASS	SUB- CLASS	TRANSI YES	ATION NO
,	AC					,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,		T
	AD				 			

OTHER DOCUMENTS (Including Author, Title, Date, Pertinent Pages, Etc.)				
MS	AE	Dongheui Lee et al.; "A Reliable Position Estimation Method of the Service Robot by the Map Matching"; Proceedings of the 2003 IEEE International Conference on Robotics & Automation, Sept. 14-19, 2003; pp. 2830-2835.	~	

EXAMINER	/Manav Seth/	DATE CONSIDERED	01/24/2007
*EXAMINER: citation if not in c	Initial if document considered, whether or not cit	ation is in conformance with I	MPEP 609; Draw line through
	conformance and not considered. Include copy of	f this form with next commun	dication to applicant.